

Assessing the Shared Automated Vehicle's fleet size using flow optimization in an interurban demand project

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**Driving2Driverless
project**

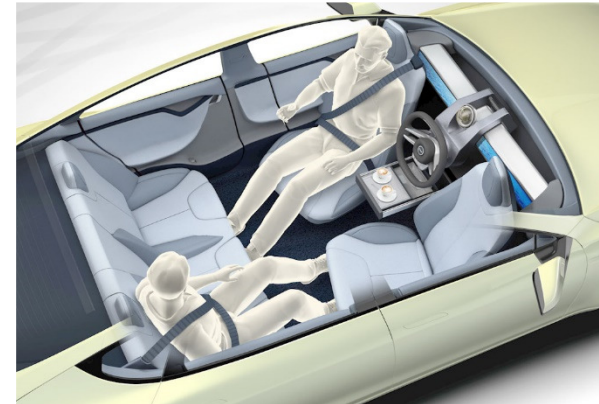


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Outline

- ❑ Introduction
- ❑ Driving2Driverless project
- ❑ Assessing fleet size
- ❑ Closing remarks
- ❑ Next steps



Rinspeed XchangE concept

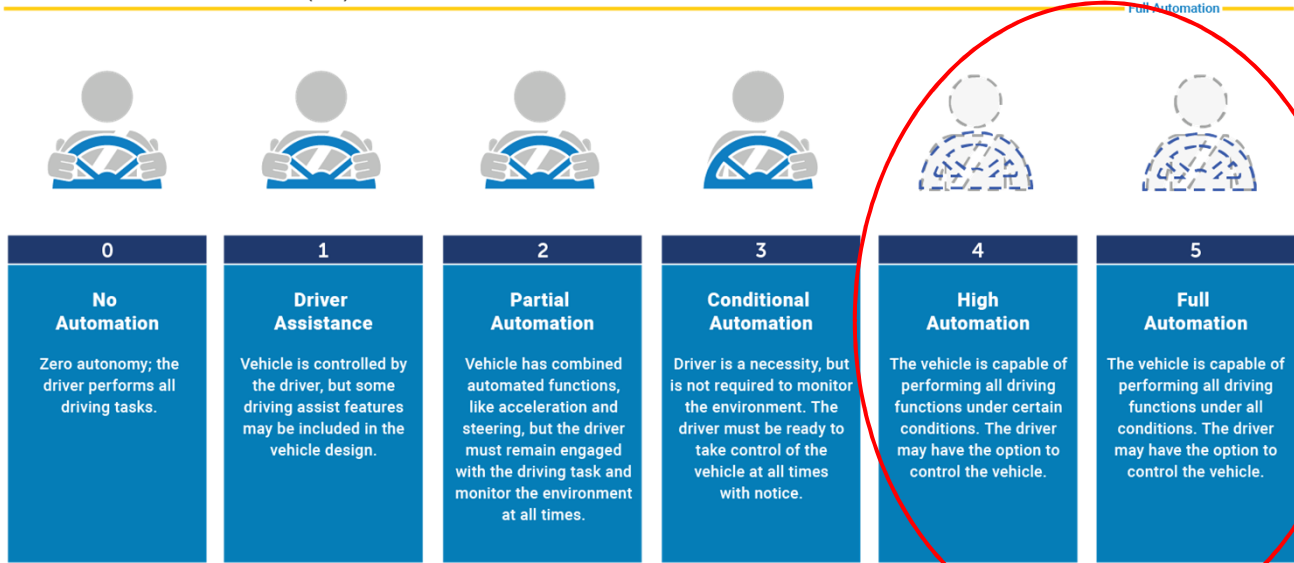


Wepod electric driverless bus, Netherlands

Introduction

□ Automation is becoming part of driving

SOCIETY OF AUTOMOTIVE ENGINEERS (SAE) AUTOMATION LEVELS



Self-driving vehicles
(autonomous)

Potential of AV's

The use of autonomous vehicles (AV) can potentially affect:

- ❑ Road safety (decrease the number of accidents EU Vision Zero);
- ❑ Mobility (namely to elders and people with disabilities);
- ❑ Productivity (perform other activities while traveling);
- ❑ Environmental (perform other activities while traveling);

The use of a shared fleet of AV's (SAV) can increase:

- ❑ Access to AV technology
(lower car ownership);
- ❑ Access to mobility
(for those living in less dense areas);



Interurban mobility

- The use of SAV has been studied in urban contexts (namely inside metropolitan areas);
- Heterogeneous regions (with low density areas) are more likely to benefit from the introduction of a SAV system;

Aim of the D2D project:

Look into a long term scenario where all demand is provided by Autonomous vehicles;

Interurban movements in **Coimbra and Aveiro**;

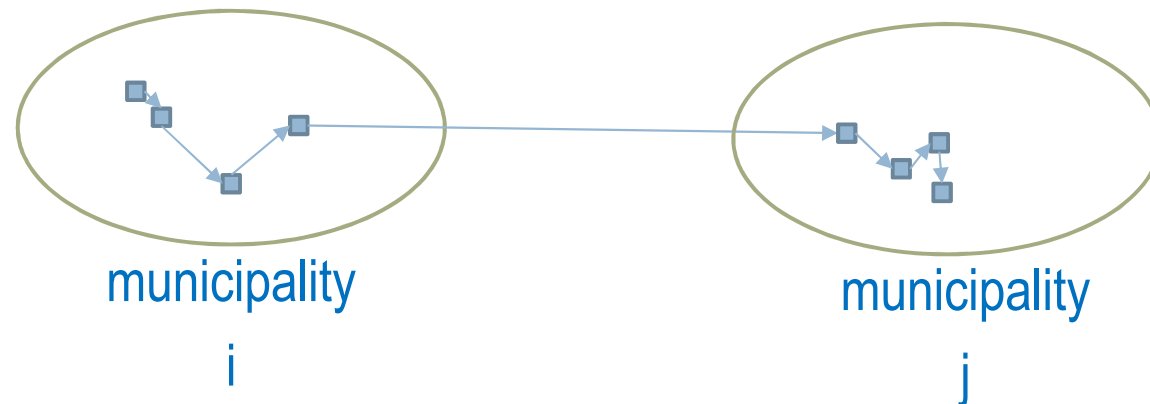
Address the **different components** (routing, network modeling, charging and parking).

Assessing fleet size

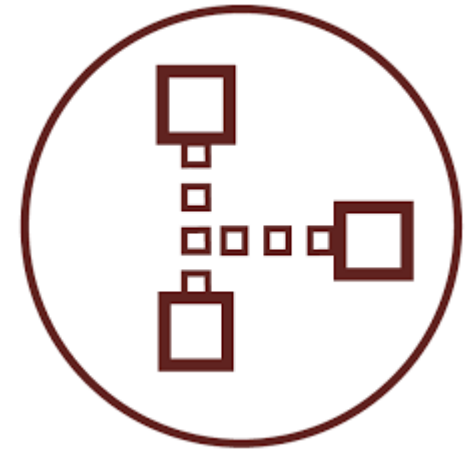
(Preliminary study: optimal fleet, profit)

Transport service

- ❑ Shared Autonomous Vehicles (SAV)
- ❑ Interurban transportation market;
- ❑ The trips are between municipalities;
- ❑ It is considered that vehicles gather clients inside the municipality of origin, travel to the municipality of destination and distribute clients to their individual destinations;



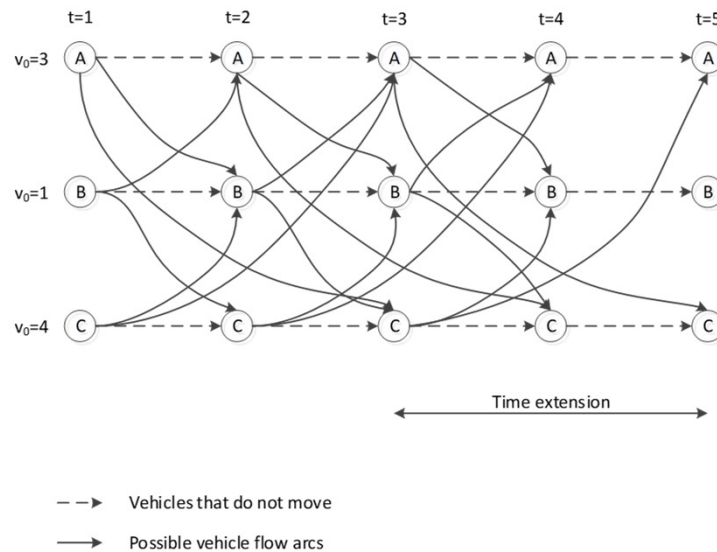
Scenarios



- 1) A fleet of minibus 16 seats (autonomous, non-autonomous)
- 2) A fleet of autonomous vehicles with a 4 seat capacity
- 3) The importance of electric battery range constraint
- 4) Turn on and off municipalities (decided by optimization)
- 5) A mixed fleet of autonomous vehicles (4 and 16 seat capacity decided by optimization)

MIP model

- ❑ Routing np-hard
- ❑ Considers flows of vehicles (aggregated values)
- ❑ Time-space network
- ❑ Nodes represent municipalities; Edges represent flows
- ❑ Vehicles can relocate



MIP model

Objective function (maximize profit)

$$\begin{aligned} \max(\Pi) = & \sum_{(i_t, j_{t+t_{ij}}) \in A_1} p(i, j) \cdot [D(i_t, j_{t+t_{ij}}) - k(i_t, j_{t+t_{ij}})] \\ - & \sum_{(i_t, j_{t+t_{ij}}) \in A_1} c(i, j) \cdot (x(i_t, j_{t+t_{ij}}) + y(i_t, j_{t+t_{ij}})) - (c_{driver} + c_v) \cdot v \end{aligned}$$

Subject to:

(1) Ensure the conservation of vehicle flows.

$$\begin{aligned} s(i_{t-1}, i_t)_{(i_{t-1}, i_t) \in A_2} + \sum_{(j_{t-t_{ij}}, i_t) \in A_1} x(j_{t-t_{ij}}, i_t) + \sum_{(j_{t-t_{ij}}, i_t) \in A_1} y(j_{t-t_{ij}}, i_t) \\ - \sum_{(i_t, j_{t+t_{ij}}) \in A_1} x(i_t, j_{t+t_{ij}}) - \sum_{(i_t, j_{t+t_{ij}}) \in A_1} y(i_t, j_{t+t_{ij}}) - s(i_t, i_{t+1})_{(i_t, i_{t+1}) \in A_2} \\ = 0, \forall i_t \in V | t > 0 \end{aligned}$$

(2) The number of persons transported by vehicles do not overpass its capacity

$$D(i_t, j_{t+t_{ij}}) - k(i_t, j_{t+t_{ij}}) \leq m \times x(i_t, j_{t+t_{ij}}), \forall (i_t, j_{t+t_{ij}}) \in A_1$$

(3) Rejected demand cannot overpass demand

$$k(i_t, j_{t+t_{ij}}) \leq D(i_t, j_{t+t_{ij}}), \forall (i_t, j_{t+t_{ij}}) \in A_1$$

Scenarios	models
1	Model constrains 1 to 4
2	Model constrains 1 to 4
3	Model constrains 1 to 4 and 5
4	Model constrains 1 to 4 and 6
5	Model constrains 1 to 4 adapted for two vehicle types; the service provider chooses the vehicle to send

(4) decide the number and position of vehicles at the first instant

$$\sum_{i \in N} s(i_0, i_1) = v$$

(5) the number of kms moving (in aggregate numbers) must be less or equal than the capacity of batteries.

$$\sum_{t=1}^{t=k} x(i_t, j_{t+t_{ij}}) \cdot d_{ij} + \sum_{t=1}^{t=k} y(i_t, j_{t+t_{ij}}) \cdot d_{ij} \leq R_0 \cdot v + C_r \cdot \sum_{t=1}^{t-k} s(i_t, i_{t+1}), \forall k \in I, (i_t, j_{t+t_{ij}}) \in A_1, (i_t, i_{t+1}) \in A_2$$

(6) the optimization model decides which municipalities are worth to explore through a profit point of view.

$$D(i_t, j_{t+t_{ij}}) = D'(i_t, j_{t+t_{ij}}) \times a(i, j), \forall (i_t, j_{t+t_{ij}}) \in A_1$$

$$a(i, j) \leq r(j), \forall i, j \in N$$

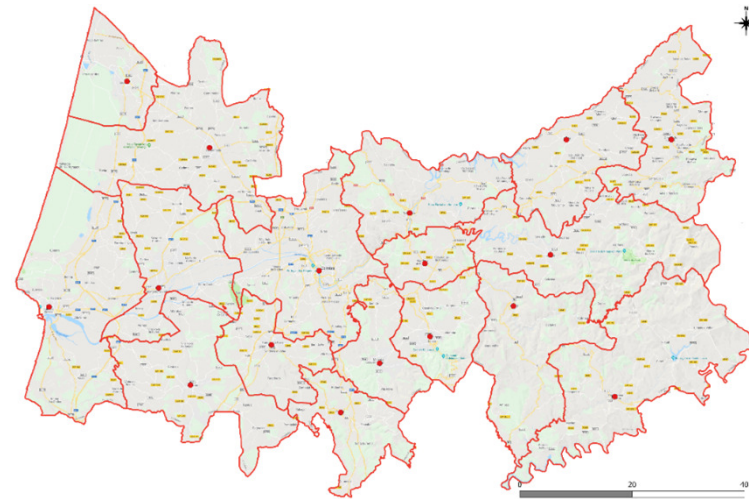
$$a(i, j) \leq r(i), \forall i, j \in N$$

$$a(i, j) \geq r(i) - M(1 - r(j)), \forall i, j \in N$$

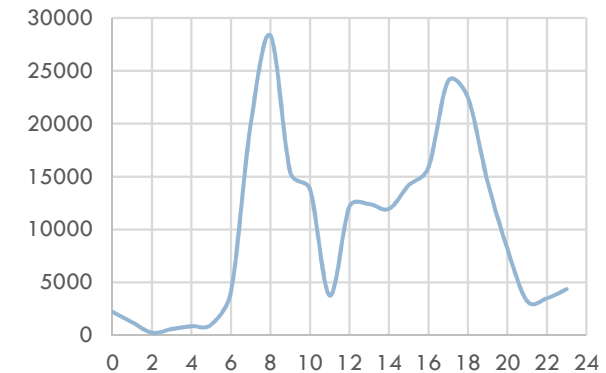
$$r(i) \in \{0, 1\}$$

Case study

- Region of Coimbra (17 municipalities)



- Demand gathered from survey IMM2008
total intermunicipal trips: 238490
average distance: 32.5 km;
average speed \approx 60km/h;



- Different demand values considered

Service price and costs

□ Service price considered: 10cts/km

(less than half of the urban service drivenow lisboa 27cts/min, considering an average speed of 60km/h)

□ Vehicles:

	Minibus (Iveco Daily electric)	Car (Renault Zoe)
Capacity	16 passengers	4 passengers
Price	68000€	23195€
Depreciation (20% depreciation on the first 3 years)	37€ /day	13€ /day
Range	250km	250km
Normal charging rate	0.42km/min	1km/min
Running cost	7€/100km	4€/100km

Results - Mixed fleet vs Mono fleet

	No rejection		
	D (%)	#vehicles	profit(k€)
Autonomous car	10	743	78
	25	3388	405
	100	6715	813
Autonomous minibus	10	391	70
	25	1241	423
	100	2347	858

- Profit increase due to efficient use of capacity.

	D (%)	#cars	#minibus	Profit(k€)
Mixed fleet	10	285	141	81
	25	590	857	431
	100	964	1767	867

Allowing trip rejection

	No rejection			With trip rejection		
	D (%)	#vehicles	profit	#vehicles	profit	#rejected trips
Autonomous car	10	743	77542	(-94)	77979	210 (0.88%)
	25	3388	404770	(-172)	405446	532 (0.45%)
	100	6715	813007	(-273)	814021	923 (0.39%)
Autonomous minibus	10	391	69851	(-120)	72932	992 (4.18%)
	25	1241	422814	(-162)	425104	1506 (1.26%)
	100	2347	858217	(-218)	860445	2463 (1.03%)

□ Trip rejection leads to 1% increase in profit

□ Low service level

Electric capacity constraint

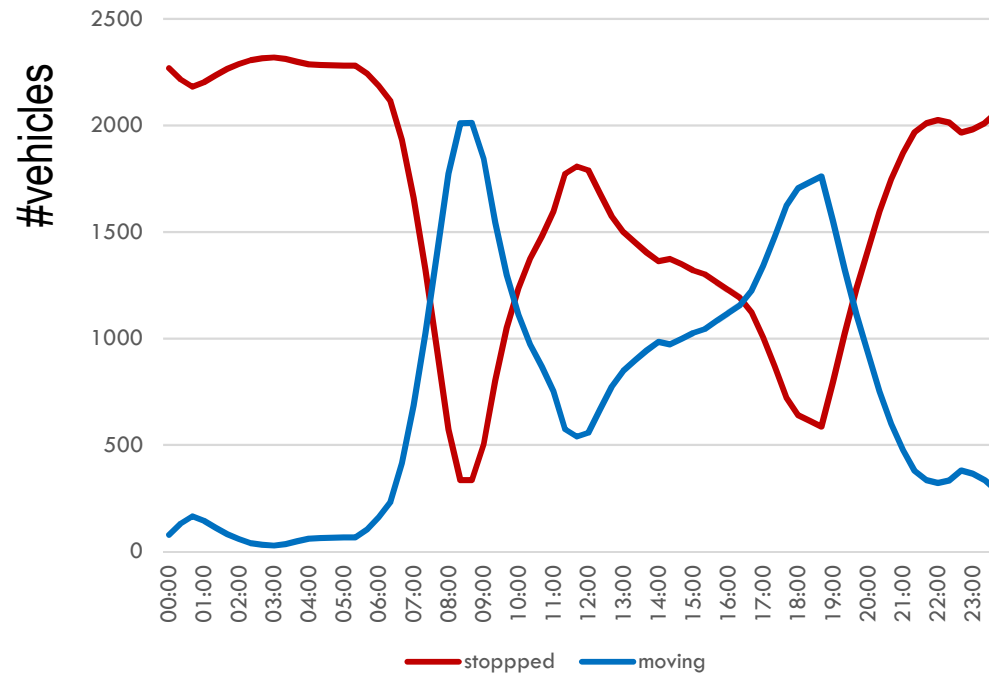
- ❑ The electric capacity constraint doesn't affect the results (considering that the vehicle charges every time it stops; no limitations in number of chargers and location)

2347 vehicles

599551 kms

avg: **256** km/vehicle

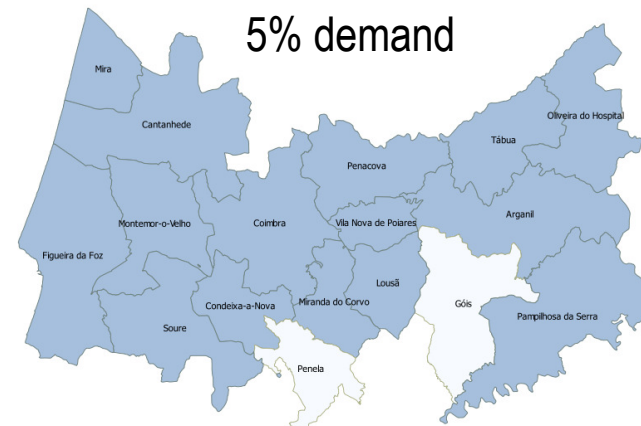
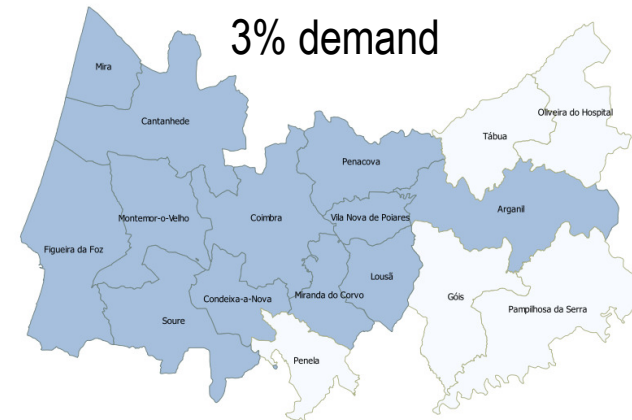
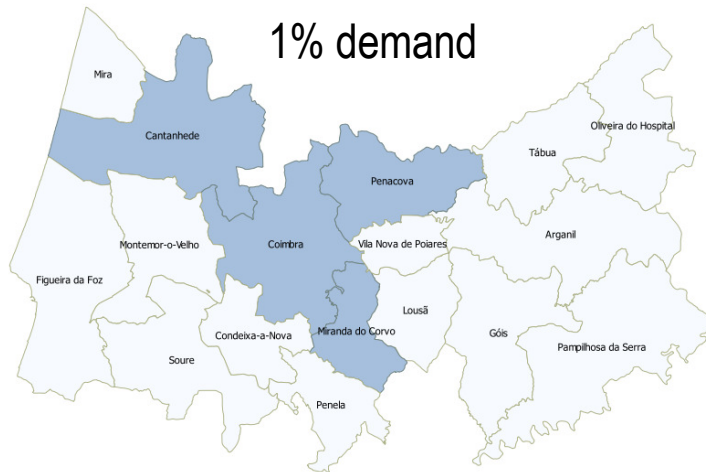
Initial charge: **250**km



Turn on-off municipalities

- The turn on off restriction is used activated for low demand levels (once there is no fixed cost associated to service expansion)

Autonomous minibus



Closing remarks

- The use of a SAV system for interurban trips is profitable (daily profit rounding 800k€ for Coimbra region);
- The number of vehicles needed to satisfy all interurban potential demand in Coimbra region are 6715 cars or 2347 minibus;
- The electric battery constraint is not important if number and location of charging stations are considered unlimited;
- Allowing trip rejection leads to a increase of 1% in profit;

Next research steps

- ❑ Expand the analysis to the **region of Aveiro**;
- ❑ Introduce pick up and delivery time;
- ❑ add maintenance cost;
- ❑ Consider the **train** as an alternative mode;
- ❑ Include **discrete choice model** inside the optimization model.

Thank You!

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**Driving2Driverless
project**

Cofinanciado por:



UNIAO EUROPEIA
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